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1. **DYMIR: A code for generating dynamic model of robots**  
Cesareo, G.; Nicolo, F.; Nicosia, S.;  
Robotics and Automation. Proceedings. 1984 IEEE International Conference on  
Volume 1, Mar 1984 Page(s):115 - 120  
IEEE CNF
2. **Semiconductors: The key to computational plenty**  
Jones, M.E.; Holton, W.C.; Stratton, R.;  
Proceedings of the IEEE  
Volume 70, Issue 12, Dec. 1982 Page(s):1380 - 1409  
IEEE JNL
3. **Novel active connector for modular robotic systems**  
Badescu, M.; Mavroidis, C.;  
Mechatronics, IEEE/ASME Transactions on  
Volume 8, Issue 3, Sept. 2003 Page(s):342 - 351  
IEEE JNL
4. **Movement control of two-wheeled mobile robots using visual information**  
Yasuda, G.; Ge Bin;  
Robotics, Intelligent Systems and Signal Processing, 2003. Proceedings. 2003  
IEEE International Conference on  
Volume 1, 8-13 Oct. 2003 Page(s):576 - 581 vol.1  
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... once again when Takara re-releases the **changeable robot** in March 2003. ...

The device locks into the back of the GBA and uses flash **memory** cards to ...

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... The real Constructions (going by **memory**), but The plastic is really sub-par.

... is that The "**Changeable robot**" Set? I've got that Devvy and Superior. ...

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compete for space in computer **memory**. To run on an existing ... environment is

**changeable. Robot** learning has characteristics that ...

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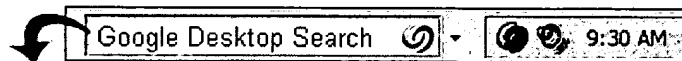
solved by using a **changeable robot** interface module that from the other side

connects to the ... the main part of the code handles initializations, **memory** ...

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